



Partial Differential Equations. – *Nonlinear Fokker–Planck equations as smooth Hilbertian gradient flows*, by VIOREL BARBU and MICHAEL RÖCKNER, accepted on 19 September 2025.

In memory of Giuseppe Da Prato.

ABSTRACT. – Under suitable assumptions on $\beta : \mathbb{R} \rightarrow \mathbb{R}$, $D : \mathbb{R}^d \rightarrow \mathbb{R}^d$, and $b : \mathbb{R}^d \rightarrow \mathbb{R}$, the nonlinear Fokker–Planck equation $u_t - \Delta\beta(u) + \operatorname{div}(Db(u)u) = 0$, in $(0, \infty) \times \mathbb{R}^d$ where $D = -\nabla\Phi$, can be identified as a smooth gradient flow $\frac{d^+}{dt} u(t) + \nabla E_{u(t)} = 0$, $\forall t > 0$. Here, $E : \mathcal{P}^* \cap L^\infty(\mathbb{R}^d) \rightarrow \mathbb{R}$ is the energy function associated with the equation, where $\mathcal{P}^*$ is a certain convex subset of the space of probability densities. $\mathcal{P}^*$ is invariant under the flow and ∇E_u is the gradient of E , that is, the tangent vector field to $\mathcal{P}$ at u defined by $\langle \nabla E_u, z_u \rangle_u = \operatorname{diff} E_u \cdot z_u$ for all vector fields z_u on $\mathcal{P}^*$, where $\langle \cdot, \cdot \rangle_u$ is a scalar product on a suitable tangent space $\mathcal{T}_u(\mathcal{P}^*) \subset \mathcal{D}'(\mathbb{R}^d)$.

KEYWORDS. – Fokker–Planck equation, gradient flow, semigroup, stochastic equations, tensor metric.

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1. INTRODUCTION

We are concerned here with the nonlinear Fokker–Planck equation (NFPE)

$$(1.1) \quad \begin{aligned} u_t - \Delta\beta(u) + \operatorname{div}(Db(u)u) &= 0 \quad \text{in } (0, \infty) \times \mathbb{R}^d, \\ u(0, x) &= u_0(x), \quad x \in \mathbb{R}^d, \end{aligned}$$

where $\beta : \mathbb{R} \rightarrow \mathbb{R}$, $D : \mathbb{R}^d \rightarrow \mathbb{R}^d$, $d \geq 1$, and $b : \mathbb{R} \rightarrow \mathbb{R}$ are assumed to satisfy the following hypotheses:

- (i) $\beta \in C^1(\mathbb{R})$, $\beta(0) = 0$, $0 < \gamma_1 \leq \beta'(r) \leq \gamma_2 < \infty$, $\forall r \in \mathbb{R}$.
- (ii) $b \in C_b(\mathbb{R}) \cap C^1(\mathbb{R})$ and $b(r) \geq b_0 > 0$, $|b'(r)r + b(r)| \leq \gamma_3 < \infty$, $\forall r \in \mathbb{R}$.
- (iii) $D \in L^\infty(\mathbb{R}^d; \mathbb{R}^d) \cap W_{\operatorname{loc}}^{1,1}(\mathbb{R}^d; \mathbb{R}^d)$ and $\operatorname{div} D \in L^2(\mathbb{R}^d) + L^\infty(\mathbb{R}^d)$.
- (iv) $D = -\nabla\Phi$, where $\Phi \in C(\mathbb{R}^d) \cap W_{\operatorname{loc}}^{2,1}(\mathbb{R}^d)$, $\Phi \geq 1$, $\lim_{|x| \rightarrow \infty} \Phi(x) = +\infty$, $\Phi^{-m} \in L^1(\mathbb{R}^d)$ for some $m \geq 2$.

NFPE (1.1) is modeling the so-called *anomalous diffusion* in statistical physics (see, e.g., [13]) and also describes the dynamics of Itô stochastic processes in terms of their probability densities. In fact, if u is a distributional solution to (1.1), such that $t \rightarrow u(t)dx$ is weakly continuous and $u(t) \in \mathcal{P}$, $\forall t \geq 0$, then there is a probabilistically weak solution X_t to the McKean–Vlasov stochastic differential equation

$$(1.2) \quad dX_t = D(X_t)b(u(t, X_t))dt + \left(\frac{2\beta(u(t, X_t))}{u(t, X_t)} \right)^{\frac{1}{2}} dW_t,$$

on a probability space $(\Omega, \mathcal{F}, \mathbb{P}, W_t)$ with normal filtration $(\mathcal{F}_t)_{t \geq 0}$. More exactly, one has $\mathcal{L}_{X_t} \equiv u(t, x)$, where $\mathcal{L}_{X_t}$ is the density of the marginal law $\mathbb{P} \circ X_t^{-1}$ of X_t with respect to the Lebesgue measure (see [7, 10]).

The function $u : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}$ is called a *mild solution* to (1.1) if it is L^1 -continuous, that is, $u \in C([0, \infty); L^1(\mathbb{R}^d))$, and

$$(1.3) \quad u(t) = \lim_{h \rightarrow 0} u_h(t) \quad \text{in } L^1(\mathbb{R}^d), \quad \forall t \geq 0$$

where, for each $T > 0$, $u_h : (0, T) \rightarrow L^1(\mathbb{R}^d)$ is defined by

$$(1.4) \quad \begin{aligned} u_h(t) &= u_h^j, \quad t \in [jh, (j+1)h), \quad j = 0, 1, \dots, \left[\frac{T}{h}\right], \\ u_h^{j+1} + hAu_h^{j+1} &= u_h^j, \quad j = 0, 1, \dots, \left[\frac{T}{h}\right]; \quad u_h^0 = u_0. \end{aligned}$$

Here, $A : L^1(\mathbb{R}^d) \rightarrow L^1(\mathbb{R}^d)$ is the operator

$$(1.5) \quad \begin{aligned} Ay &= -\Delta\beta(y) + \operatorname{div}(Db(y)y) \quad \text{in } \mathcal{D}'(\mathbb{R}^d); \quad y \in D(A), \\ D(A) &= \{y \in L^1(\mathbb{R}^d); -\Delta\beta(y) + \operatorname{div}(Db(y)y) \in L^1(\mathbb{R}^d)\}. \end{aligned}$$

As shown in [9] (see also [7, 8, 10]), under the above hypotheses (as a matter of fact, for less restrictive assumptions), the domain $D(A)$ is dense in $L^1(\mathbb{R}^d)$, that is, $\overline{D(A)} = L^1(\mathbb{R}^d)$, and the operator A is m -accretive in $L^1(\mathbb{R}^d)$, which means that (see, e.g., [4, 5])

$$\begin{aligned} R(I + \lambda A) &= L^1(\mathbb{R}^d), \quad \forall \lambda > 0, \\ \|(I + \lambda A)^{-1}y_1 - (I + \lambda A)^{-1}y_2\|_{L^1(\mathbb{R}^d)} &\leq \|y_1 - y_2\|_{L^1(\mathbb{R}^d)}, \\ &\quad \forall \lambda > 0, \quad y_1, y_2 \in L^1(\mathbb{R}^d). \end{aligned}$$

Then, by the Crandall–Liggett theorem (see [4], [5, p. 56]), the Cauchy problem

$$(1.6) \quad \frac{du}{dt} + Au = 0, \quad t \geq 0; \quad u(0) = u_0,$$

has, for each $u_0 \in L^1(\mathbb{R}^d)$, a unique solution $u = u(t, u_0)$ in the mild sense (1.3)–(1.4).

Equivalently,

$$(1.7) \quad u(t, u_0) = \lim_{n \rightarrow \infty} \left(I + \frac{t}{n} A \right)^{-n} u_0 \quad \text{in } L^1(\mathbb{R}^d),$$

uniformly on the compact intervals of $[0, \infty)$.

Moreover, the map $t \rightarrow u(t, u_0)$, denoted by $S(t)u_0$, is a *continuous semigroup* of contractions on $L^1(\mathbb{R}^d)$, that is,

$$\begin{aligned} S(t+s) &= S(t)S(s) \quad \text{for all } s, t \geq 0, \\ \|S(t)u_1 - S(t)u_2\|_{L^1(\mathbb{R}^d)} &\leq \|u_1 - u_2\|_{L^1(\mathbb{R}^d)}, \quad \forall t \geq 0, u_1, u_2 \in L^1(\mathbb{R}^d), \\ \lim_{t \rightarrow 0} S(t)u_0 &= u_0 \quad \text{in } L^1(\mathbb{R}^d). \end{aligned}$$

Note also (see [7–10]) that

$$(1.8) \quad S(t)(L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)) \subset L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d), \quad \forall t \geq 0,$$

$$(1.9) \quad S(t)(L^1(\mathbb{R}^d) \cap L^1(\mathbb{R}^d; \Phi dx)) \subset L^1(\mathbb{R}^d) \cap L^1(\mathbb{R}^d; \Phi dx),$$

$$(1.10) \quad S(t)u_0 \in L^\infty((0, T) \times \mathbb{R}^d), \quad \forall T > 0, \forall u_0 \in L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d),$$

and $S(t)\mathcal{P} \subset \mathcal{P}$, $\forall t \geq 0$, where

$$(1.11) \quad \mathcal{P} = \left\{ y \in L^1(\mathbb{R}^d), y(x) \geq 0, \text{ a.e. } x \in \mathbb{R}^d; \int_{\mathbb{R}^d} y(x) dx = 1 \right\}.$$

We also note that, though $t \rightarrow u(t) = S(t)u_0$ is not differentiable, it is, however, a Schwartz-distributional solution to (1.1), that is,

$$(1.12) \quad \begin{aligned} \int_0^\infty \int_{\mathbb{R}^d} (u\varphi_t + \beta(u)\Delta_x \varphi + b(u)u D \cdot \nabla_x \varphi) dx dt \\ + \int_{\mathbb{R}^d} u_0(x) \varphi(0, x) dx = 0, \end{aligned}$$

for all $\varphi \in C_0^\infty([0, \infty) \times \mathbb{R}^d)$.

Moreover, as shown in [9] (see also [10]), $S(t)u_0$ is the unique distributional solution to NFPE (1.1) in the class of functions

$$u \in L^1((0, \infty) \times \mathbb{R}^d) \cap L^\infty((0, \infty) \times \mathbb{R}^d)$$

such that $t \rightarrow u(t)dx$ is weakly continuous on $[0, \infty)$. In particular, this implies (see, e.g., [9] and [10, Chapter 5]) that the McKean–Vlasov equation (1.2) has a unique strong solution X_t with the marginal law $u(t, \cdot)$.

The purpose of this work is to represent the solution $t \rightarrow S(t)u_0$ to (1.1) as a *subgradient flow* of the entropy functional (energy)

$$(1.13) \quad \begin{aligned} E(u) &= \int_{\mathbb{R}^d} (\eta(u(x)) + \Phi(x)u(x)) dx, \quad u \in \mathcal{P} \cap L^\infty(\mathbb{R}^d) \cap L^1(\mathbb{R}^d; \Phi dx), \\ \eta(r) &= \int_0^r \int_1^s \frac{\beta'(\tau)}{\tau b(\tau)} d\tau ds, \quad r \geq 0, \end{aligned}$$

with the tangent space $\mathcal{T}_u(\mathcal{P}^*) \subset \mathcal{D}'(\mathbb{R}^d)$ defined in (3.1) below, for $u \in \mathcal{P}^*$. Here,

$$(1.14) \quad \mathcal{P}^* = \left\{ u \in \mathcal{P} \cap L^\infty \cap L^1(\mathbb{R}^d; \Phi dx); \sqrt{u} \in H^1(\mathbb{R}^d), \frac{\psi}{u} \in L^1(\mathbb{R}^d) \right\},$$

for some $\psi \in \mathcal{X}$

where we set $\frac{1}{0} := +\infty$ and

$$(1.15) \quad \mathcal{X} = \left\{ \psi \in C^2(\mathbb{R}^d) \cap C_b(\mathbb{R}^d) \cap L^1(\mathbb{R}^d), \psi > 0, \frac{\nabla \psi}{\psi} \in L^\infty(\mathbb{R}^d) \right\}.$$

We also note that the function E is convex and lower semicontinuous on $L^2(\mathbb{R}^d)$ with the domain

$$D(E) = \{u \in \mathcal{P} \cap L^\infty(\mathbb{R}^d) \cap L^\infty \cap L^1(\mathbb{R}^d; \Phi dx)\}.$$

The class $\mathcal{X}$ is clearly nonempty and, in particular, it contains all functions ψ of the form $\psi(x) = (\alpha_1|x|^m + \alpha_2)^{-1}$, α_1, α_2 and $m > d$, and, therefore, since $\mathcal{X}$ is an algebra containing the constants, it is a rich class of functions. Hence, so is $\mathcal{P}^*$ since if $\psi \in \mathcal{X}$, $\psi > 0$, $u := \psi^2(\int_{\mathbb{R}^d} \psi^2 dx)^{-1}$ is easily checked to be in $\mathcal{P}^*$. We also note that $\mathcal{P}^*$ is convex.

We recall (see, e.g., [20]) that if $F : \mathcal{X} \rightarrow]-\infty, +\infty]$ is a lower semicontinuous function on the metric space $(\mathcal{X}, \rho)$, a gradient flow associated with F is the function $u : (0, \infty) \rightarrow \mathcal{X}$ given by $u(t) = \lim_{h \rightarrow 0} u_h(t)$ uniformly on compact intervals where

$$(1.16) \quad \begin{aligned} u_h(t) &= u_h^j, \quad \forall t \in [(j-1)h, jh), \quad j = 1, 2, \dots, \\ y_h^{j+1} &\in \arg \min \left\{ F(y) + \frac{1}{2h} \rho^2(y, u_h^j); y \in \mathcal{X} \right\}. \end{aligned}$$

Formally, the flow $t \rightarrow u(t)$ is a generalized solution (in the sense of a finite difference scheme approximation) to the evolution equation

$$(1.17) \quad \frac{du(t)}{dt} = -\nabla F_{u(t)}, \quad t > 0,$$

where ∇F_u is the gradient of F at u in some generalized sense.

One spectacular application of this idea was developed in the work of Jordan, Kinderlehrer, and Otto [14] where the linear Fokker–Planck equation with $\beta(u) \equiv u$, $b(u) \equiv 1$ is represented in the variational form (1.17), where $\mathcal{X}$ is the space $\mathcal{P}$ endowed with the Wasserstein metric and F is the function (1.13). Later on, Otto [16] extended this construction to porous media equations. The general theory of gradient flows in the Wasserstein spaces was developed in the book of Ambrosio, Gigli, and Savaré [7]. More precisely, the gradient flow representation means that, for $u(t) = S(t)u_0$, $u_0 \in \mathcal{P}^*$, we have

$$(1.18) \quad \frac{d}{dt} u(t) = -\nabla E_{u(t)}, \quad t > 0,$$

where $\nabla E_u \in \mathcal{T}_u(\mathcal{P}^*)$ is the gradient of E in the sense of the Riemannian type geometry of $\mathcal{P}$ to be defined later on. Such a result was recently established in [17] on the manifold $\mathcal{P}$ endowed with the topology of weak convergence of probability measures and tangent bundle $L^2(\mathbb{R}^d; \mathbb{R}^d; \mu)_{\mu \in \mathcal{P}}$ (see also [1, 2, 15, 18, 19]) and in the fundamental work [16] for the classical porous media equation. Here, to represent the Fokker–Planck equation in the variational form (1.17), we shall proceed in a different way. Namely, we organize the space $\mathcal{P}^*$ as a Riemannian manifold by endowing its tangent space $\mathcal{T}_u(\mathcal{P}^*)$ at $u \in \mathcal{P}^*$ with a convenient Hilbertian structure with scalar product (metric tensor $\langle \cdot, \cdot \rangle_u$). Then one defines the gradient $\nabla E_u \in \mathcal{F}_u(\mathcal{P}^*)$ by the formula

$$\langle \nabla E_u, z \rangle_u = E'(u, z), \quad \forall z \in \mathcal{T}_u(\mathcal{P}^*), \quad u \in \mathcal{P}^*,$$

where $E'(u, z)$ is the directional derivative of E_u and

$$\nabla E_u = -\Delta \beta(u) + \operatorname{div} (Db^*(u)) \in H^{-1}.$$

This implies also that the flow $u(t) = S(t)u_0$ given by (1.7) is a.e. differentiable on $(0, \infty)$ in the norm of the Sobolev space $H^{-1} = H^{-1}(\mathbb{R}^d)$. This is the principal difference of our result compared with the Wasserstein based construction (1.16). In the later case, the gradient flow $S(t)$ is only continuous in L^1 , but not differentiable in any convenient Banach space. This result is based on the smoothing effect on initial data of the semigroup $S(t)$ in the space $H^{-1}(\mathbb{R}^d)$ which will be proved in Section 1. As a matter of fact, the space $H^{-1}(\mathbb{R}^d)$ is a viable alternative to $L^1(\mathbb{R}^d)$ for proving the well-posedness of NFPE (1.1). In fact, as seen below, the operator (1.5) has a quasi- m -accretive version in $H^{-1}(\mathbb{R}^d)$, which generates a C_0 -semigroup of quasi-contractions which coincides with $S(t)$ on $L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$.

One limitation of our approach might be that the gradient ∇E_u is defined on a subset $\mathcal{P}^*$ of the space $\mathcal{P}$ which implies that the flow $u(t) = S(t)u_0$ can be identified as a gradient flow only for solutions $u(t)$ with the property that $u(t) \in \mathcal{P}^*$, $\forall t \geq 0$. This happens, however, for equation (1.1) under hypotheses (i)–(iv).

We recall that (see, e.g., [4, 5]), if H is a Hilbert space with the scalar product $(\cdot, \cdot)_H$ and norm $|\cdot|$, the operator $B : D(B) \subset H \rightarrow H$ is said to be m -accretive if

$$(Bu_1 - Bu_2, u_1 - u_2) \geq 0, \quad \forall u_i \in D(B), \quad i = 1, 2,$$

and $R(I + \lambda B) = H$, $\forall \lambda > 0$. It is said to be quasi m -accretive if $B + \omega f$ is m -accretive for some $\omega \geq 0$.

Notation. $L^p(\mathbb{R}^d)$, $1 \leq p \leq \infty$ (denoted by L^p), is the space of Lebesgue measurable and p -integrable functions on $\mathbb{R}^d$, with the standard norm $|\cdot|_p$. $(\cdot, \cdot)_2$ denotes the inner product in L^2 . By L^p_{loc} we denote the corresponding local space. Let $C^k(\mathbb{R})$ denote the space of continuously differentiable functions up to order k and $C_b(\mathbb{R})$ the space of continuous and bounded functions on $\mathbb{R}$. For any open set $\mathcal{O} \subset \mathbb{R}^m$, let $W^{k,p}(\mathcal{O})$, $k \geq 1$, denote the standard Sobolev space on $\mathcal{O}$ and by $W^{k,p}_{\text{loc}}(\mathcal{O})$ the corresponding local space. We set $W^{1,2}(\mathcal{O}) = H^1(\mathcal{O})$, $W^{2,2}(\mathcal{O}) = H^2(\mathcal{O})$, $H^1_0(\mathcal{O}) = \{u \in H^1(\mathcal{O}), u = 0 \text{ on } \partial\mathcal{O}\}$, where $\partial\mathcal{O}$ is the boundary of $\mathcal{O}$. By $H^{-1}(\mathcal{O})$ we denote the dual space of $H^1_0(\mathcal{O})$ (of $H^1(\mathbb{R}^m)$, respectively, if $\mathcal{O} = \mathbb{R}^m$). We shall also set $H^1 = H^1(\mathbb{R}^d)$ and $H^{-1} = H^{-1}(\mathbb{R}^d)$. $C^\infty_0(\mathcal{O})$ is the space of infinitely differentiable real-valued functions with compact support in $\mathcal{O}$ and $\mathcal{D}'(\mathcal{O})$ is the dual of $C^\infty_0(\mathcal{O})$, that is, the space of Schwartz distributions on $\mathcal{O}$. $\text{Lip}(\mathbb{R})$ is the space of real-valued Lipschitz functions on $\mathbb{R}$ with the norm denoted by $|\cdot|_{\text{Lip}}$. The space H^{-1} is endowed with the scalar product

$$\langle y_1, y_2 \rangle_{-1} = ((I - \Delta)^{-1} y_1, y_2)_2, \quad \forall y_1, y_2 \in H^{-1},$$

and the Hilbert norm $|y|_{-1}^2 = \langle y, y \rangle_{-1}$. By ${}_{H^{-1}}(\cdot, \cdot)_{H^1}$ we denote the duality pairing on $H^1 \times H^{-1}$. If Y is a Banach space, then $C([0, \infty); Y)$ is the space of continuous functions $y : [0, \infty) \rightarrow Y$ and $C_w([0, \infty); Y)$ is the space of weakly continuous Y -valued functions. Furthermore, let $C^\infty_0([0, \infty) \times \mathbb{R}^d)$ denote the space of all $\varphi \in C^\infty([0, \infty) \times \mathbb{R}^d)$ such that $\text{support } \varphi \subset K$, where K is compact in $[0, \infty) \times \mathbb{R}^d$. If $u : [0, \infty) \rightarrow H^{-1}$ is a given function, we shall denote its H^{-1} -strong derivative in t by $\frac{du}{dt}(t)$, and the right derivative by $\frac{d^+}{dt} u(t)$. We shall also use the following notations:

$$\begin{aligned} \beta'(r) &\equiv \frac{d}{dr} \beta(r), \quad b'(r) \equiv \frac{d}{dr} b(r), \quad b^*(r) \equiv b(r)r, \quad r \in \mathbb{R}, \\ y_t &= \frac{\partial}{\partial t} y, \quad \nabla y = \left\{ \frac{\partial y}{\partial x_i} \right\}_{i=1}^d, \quad \Delta y = \sum_{i=1}^d \frac{\partial^2}{\partial^2 x_i} y, \\ \text{div } y &= \sum_{i=1}^d \frac{\partial y_i}{\partial x_i}, \quad y = \{y_i\}_{i=1}^d, \end{aligned}$$

for $y = y(t, x)$, $(t, x) \in [0, \infty) \times \mathbb{R}^d$, where Δ and div are taken in the sense of the distribution space $\mathcal{D}'(\mathbb{R}^d)$.

2. THE H^1 -REGULARITY OF THE SEMIGROUP $S(t)$

Consider the continuous semigroup $S(t) : L^1 \rightarrow L^1$ defined earlier by the exponential formula (1.7). Define the operator $A^* : H^{-1} \rightarrow H^{-1}$

$$(2.1) \quad A^*y = -\Delta\beta(y) + \operatorname{div}(Db^*(y)), \quad \forall y \in D(A^*),$$

with the domain $D(A^*) = H^1$. More precisely, for each $y \in H^1$, $A^*y \in H^{-1}$ is defined by

$$(2.2) \quad {}_{H^{-1}}(A^*y, \varphi)_{H^1} = \int_{\mathbb{R}^d} (\nabla\beta(y) - Db^*(y)) \cdot \nabla\varphi \, dx, \quad \forall \varphi \in H^1.$$

As mentioned earlier, the semigroup $S(t)$ is not differentiable in L^1 , but as shown below it is, however, H^{-1} -differentiable on the right on $(0, \infty)$.

Namely, we have the following theorem.

THEOREM 2.1. *Assume that hypotheses (i)–(iv) hold. Then, for each $u_0 \in \mathcal{P} \cap L^\infty$, the function $u(t) = S(t)u_0$ is in $C([0, \infty); H^{-1}) \cap C_w([0, \infty); L^2)$, it is H^{-1} -right differentiable on $(0, \infty)$ with $\frac{d^+}{dt} u(t)$ being H^{-1} -continuous from the right on $(0, \infty)$, $S(t)u_0 \in H^1$, $t > 0$, and*

$$(2.3) \quad \frac{d^+}{dt} S(t)u_0 + A^*S(t)u_0 = 0, \quad \forall t > 0.$$

Furthermore, $S(t)u_0 \in \mathcal{P} \cap L^\infty$, $\forall t \geq 0$, $\frac{d}{dt} S(t)u_0$ exists on $(0, \infty) \setminus N$, where N is an at most countable subset of $(0, \infty)$,

$$(2.4) \quad \frac{d}{dt} S(t)u_0 + A^*S(t)u_0 = 0, \quad \forall t \in (0, \infty) \setminus N,$$

and $t \rightarrow A^*S(t)u_0$ is H^{-1} -continuous on $(0, \infty) \setminus N$.

Moreover, $\sqrt{S(t)u_0} \in H^1(\mathbb{R}^d)$, a.e. $t > 0$, that is,

$$(2.5) \quad \frac{\nabla S(t)u_0}{\sqrt{S(t)u_0}} \in L^2, \quad \text{a.e. } t \in (0, \infty),$$

$$(2.6) \quad E(S(t)u_0) < \infty, \quad \text{a.e. } t \in (0, \infty),$$

for all $u_0 \in \mathcal{P}$ such that $u_0 \log u_0 \in L^1$. If $u_0 \in H^1$, then (2.3) holds for all $t \geq 0$, $t \rightarrow S(t)u_0$ is locally H^{-1} -Lipschitz, on $[0, \infty)$ and $u(t) \in H^1$, $\forall t \geq 0$.

Finally, if $u_0 \in \mathcal{P}^*$, then

$$(2.7) \quad S(t)u_0 \in \mathcal{P}^*, \quad \forall t \geq 0.$$

In particular, it follows by Theorem 2.1 that the semigroup $S(t)$ is generated by the operator $-A^*$ in the space H^{-1} .

We shall prove Theorem 2.1 in several steps, the first one being the following lemma.

LEMMA 2.2. *The operator A^* is quasi- m -accretive in H^{-1} ; that is, $A^* + \omega I$ is m -accretive for some $\omega \geq 0$.*

PROOF. We have

$$\begin{aligned}
 (2.8) \quad & \langle A^* y_1 - A^* y_2, y_1 - y_2 \rangle_{-1} \\
 &= (\beta(y_1) - \beta(y_2), y_1 - y_2)_2 - (\beta(y_1) - \beta(y_2), (I - \Delta)^{-1}(y_1 - y_2))_2 \\
 &\quad + (D(b^*(y_1) - b^*(y_2)), \nabla(I - \Delta)^{-1}(y_1 - y_2))_2 \\
 &\geq \gamma_1 |y_1 - y_2|_2^2 - \gamma_2 |y_1 - y_2|_{-1} |y_1 - y_2|_2 - |D|_\infty |b^*|_{\text{Lip}} |y_1 - y_2|_2 |y_1 - y_2|_{-1} \\
 &\geq -\omega |y_1 - y_2|_{-1}^2, \quad \forall y_1, y_2 \in D(A^*),
 \end{aligned}$$

for a suitable chosen $\omega \geq 0$ and so $A^* + \omega I$ is accretive in H^{-1} . (Here, we have used the inequality $|\nabla(I - \Delta)^{-1}(y_1 - y_2)|_2 \leq |y_1 - y_2|_{-1}$.) Now, we shall prove that $R(I + \lambda A^*) = H^{-1}$ for $\lambda \in (0, \lambda_0)$, where λ_0 is suitably chosen. For this purpose, we fix $f \in H^{-1}$ and consider the equation

$$(2.9) \quad y - \lambda \Delta \beta(y) + \lambda \operatorname{div}(D b^*(y)) = f \quad \text{in } \mathcal{D}'(\mathbb{R}^d), \quad y \in L^2.$$

The latter can be written as

$$(2.10) \quad G_\lambda(y) = (I - \Delta)^{-1} f,$$

where $G_\lambda : L^2 \rightarrow L^2$ is the operator

$$\begin{aligned}
 G_\lambda(y) &= \lambda \beta(y) + (I - \Delta)^{-1} y - \lambda (I - \Delta)^{-1} \operatorname{div}(D b^*(y)) - \lambda (I - \Delta)^{-1} \beta(y), \\
 &\quad \forall y \in L^2,
 \end{aligned}$$

which by hypotheses (i)–(iii) is continuous. Then, by (i)–(iii), we have

$$\begin{aligned}
 (G_\lambda(y_1) - G_\lambda(y_2), y_1 - y_2) &\geq \lambda \gamma_1 |y_1 - y_2|_2^2 + |y_1 - y_2|_{-1}^2 \\
 &\quad - \lambda \gamma_2 |y_1 - y_2|_{-1} |y_1 - y_2|_2 - \lambda |D|_\infty |b^*|_{\text{Lip}} |y_1 - y_2|_2 |y_1 - y_2|_{-1} \\
 &\geq \frac{1}{2} (\lambda \gamma_1 - \gamma_2^2 \lambda^2 - \lambda^2 |D|_\infty^2 |b^*|_{\text{Lip}}^2) |y_1 - y_2|_2^2 + \frac{1}{2} |y_1 - y_2|_{-1}^2 \\
 &\geq \alpha |y_1 - y_2|_2^2, \quad \forall y_1, y_2 \in L^2,
 \end{aligned}$$

for some $\alpha > 0$ and $0 < \lambda < \lambda_0$ with λ_0 sufficiently small. Hence, the operator G_λ is monotone and coercive in the space L^2 . Since it is also continuous, we infer that it is

surjective (see, e.g., [4, p. 37]) and, therefore, $R(G_\lambda) = L^2$ for $0 < \lambda < \lambda_0$. Hence, (2.10) (equivalently (2.9)) has a solution $y \in L^2$ for $\lambda \in (0, \lambda_0)$ and $\beta(y) \in H^1$. Then, by (i), it follows that $y \in H^1$ and so $y \in D(A^*)$. Hence, A^* is quasi- m -accretive in H^{-1} . ■

Lemma 2.2 implies that there is a C_0 -continuous nonlinear semigroup $S^*(t) : H^{-1} \rightarrow H^{-1}$, $t \geq 0$, which is generated by $-A^*$. This means (see, e.g., [4, p. 146] or [5, p. 56]) that

$$(2.11) \quad S^*(t)u_0 = \lim_{n \rightarrow \infty} \left(I + \frac{t}{n} A^* \right)^{-n} u_0 \quad \text{in } H^{-1}, \quad \forall t \geq 0, \quad \forall u_0 \in H^{-1},$$

uniformly on compact intervals. Moreover, for all $u_0 \in D(A^*) = H^1$, we have $S^*(t)u_0 \in D(A^*)$, $[0, \infty) \ni t \mapsto S^*(t)u_0 \in H^{-1}$ is locally Lipschitz, and

$$(2.12) \quad \frac{d^+}{dt} S^*(t)u_0 + A^* S^*(t)u_0 = 0, \quad \forall t \geq 0,$$

$$(2.13) \quad \frac{d}{dt} S^*(t)u_0 + A^* S^*(t)u_0 = 0, \quad \text{a.e. } t > 0,$$

and the function $t \rightarrow \frac{d^+}{dt} S^*(t)u_0$ is continuous from the right in the H^{-1} -topology. Taking into account (2.2), we can rewrite (2.13) as

$$(2.14) \quad \frac{d}{dt} \int_{\mathbb{R}^d} (S^*(t)u_0)(x) \varphi(x) dx + \int_{\mathbb{R}^d} (\nabla \beta(S^*(t)u_0)(x)) \\ - D(x)b^*((S^*(t)u_0)(x)) \cdot \nabla \varphi(x) dx = 0, \quad \text{a.e. } t > 0, \quad \forall \varphi \in H^1.$$

We also note that the semigroup $S^*(t)$ is quasi-contractive on H^{-1} , that is,

$$|S^*(t)u_0 - S^*(t)\bar{u}_0|_{-1} \leq \exp(\omega t) |u_0 - \bar{u}_0|_{-1}, \quad \forall t \geq 0, \quad \forall u_0, \bar{u}_0 \in H^{-1},$$

for some $\omega \geq 0$. Moreover, we have, for all $u_0 \in L^2$ and $T > 0$,

$$(2.15) \quad |S^*(t)u_0|_2^2 + \int_0^t |\nabla(S^*(s)u_0)|_2^2 ds \leq C_T |u_0|_2^2, \quad \forall t \in [0, T].$$

Here is the argument. By (2.11), we have, for all $T > 0$,

$$(2.16) \quad S^*(t)u_0 = \lim_{h \rightarrow 0} v_h(t) \quad \text{in } H^{-1}, \quad \forall t \in (0, T),$$

where

$$(2.17) \quad v_h(t) = v_h^j, \quad \forall t \in [jh, (j+1)h), \quad j = 0, 1, \dots, N_h = \left\lceil \frac{T}{h} \right\rceil, \\ v_h^{j+1} + hA^* v_h^j = v_h^j, \quad j = 0, 1, \dots, N_h; \quad v_h^0 = u_0.$$

Since $v_h^0 = u_0 \in L^2$, we get by (2.17)

$$\begin{aligned} & (\beta(v_h^{j+1}), v_h^{j+1} - v_h^j)_2 + h |\nabla \beta(v_h^{j+1})|_2^2 \\ & = h (\nabla \beta(v_h^{j+1}), Db^*(v_h^{j+1}))_2 \leq \frac{h}{2} |\nabla \beta(v_h^{j+1})|_2^2 + \frac{h}{2} (|D|^\infty |b^*|_\infty |v_h^{j+1}|_2)^2. \end{aligned}$$

By (i), this yields

$$\int_{\mathbb{R}^d} j(v_h^{j+1}) dx + \frac{1}{2} \gamma_1^2 h \sum_{k=1}^{j+1} |\nabla(v_h^k)|_2^2 \leq \int_{\mathbb{R}^d} j(u_0) dx + Ch \sum_{k=1}^{j+1} |v_h^k|_2^2,$$

where $j(r) = \int_0^r \beta(s) ds$. Since $\frac{1}{2} \gamma_1 r^2 \leq j(r) \leq \frac{1}{2} \gamma_2 r^2$, $\forall r \in \mathbb{R}$, we have

$$|v_h(t)|_2^2 + \int_0^t |\nabla v_h(s)|_2^2 ds \leq C \left(\int_0^t |v_h(s)|_2^2 ds + |u_0|_2^2 \right), \quad t \in (0, T).$$

Hence,

$$|v_h(t)|_2^2 + \int_0^t |\nabla v_h(s)|_2^2 ds \leq C |u_0|_2^2, \quad \forall t \in (0, T), \quad h > 0.$$

Therefore, by (2.16) and by the weak-lower semicontinuity of the $L^2(0, T; H^1)$ -norm, (2.15) follows. Hence, $S^*(t)u_0 \in H^1$, a.e. $t > 0$, and so, by the semigroup property, $S^*(t+s) = S^*(t)S^*(s)$, $t, s \geq 0$, we infer that $S^*(t)$ has a smoothing effect on initial data, that is,

$$(2.18) \quad S^*(t)u_0 \in H^1 = D(A^*), \quad \forall t > 0, \quad u_0 \in L^2.$$

Then, by (2.12), it follows that $t \mapsto S^*(t)u_0$ is H^{-1} -continuous on $(0, T)$ for all $u_0 \in L^2$; hence, $t \mapsto |S^*(t)u_0|_2$ is lower semicontinuous on $(0, T)$. Furthermore, (2.18) implies

$$(2.19) \quad \frac{d^+}{dt} S^*(t)u_0 + A^* S^*(t)u_0 = 0, \quad \forall u_0 \in L^2, \quad \forall t > 0,$$

and that the function $t \rightarrow \frac{d^+}{dt} S^*(t)u_0 = -A^* S^*(t)u_0$ is H^{-1} -right continuous on $(0, \infty)$. Since $S^*(\cdot)u_0 \in L^\infty(0, T; L^2) \cap C([0, T]; H^{-1})$, it follows that

$$\sup_{t \in [0, T]} |S^*(t)u_0|_2 \leq \text{ess sup}_{t > 0} |S^*(t)u_0|_2 \vee |S^*(T)u_0|_2 + |u_0|_2 < \infty$$

and hence we obtain by the uniqueness of limits that the function $t \rightarrow S^*(t)u_0$ is L^2 -weakly continuous, that is, $S^*(\cdot)u_0 \in C_w([0, T]; L^2)$, $\forall T > 0$. We set $u_h(t) = u(t+h) - u(t)$, $u(t) \equiv S^*(t)u_0$, $\forall t \in [0, T]$, $h > 0$, $u_0 \in L^2$. By (2.19), we have

$$\frac{d^+}{dt} u_h(t) + A^* u(t+h) - A^* u(t) = 0, \quad \forall t \in (0, T].$$

This yields

$$\frac{1}{2} \frac{d^+}{dt} |u_h(t)|_{-1}^2 + \langle A^*u(t+h) - A^*u(t), u_h(t) \rangle_{-1} = 0$$

and, therefore, by (2.8),

$$\frac{1}{2} \frac{d^+}{dt} |u_h(t)|_{-1}^2 \leq \omega |u_h(t)|_{-1}^2, \quad \forall t \in (0, T].$$

Hence, for all $h > 0$, we have

$$|u_h(t)|_{-1} \exp(-\omega t) \leq |u_h(s)|_{-1} \exp(-\omega s), \quad 0 < s < t < T,$$

and, therefore, the function $t \rightarrow \exp(-\omega t) |A^*S^*(t)u_0|_{-1}$ is monotonically decreasing on $(0, \infty)$ and so it is everywhere continuous on $(0, \infty)$, except for a countable set $N \subset (0, \infty)$.

Since the continuity points of $t \rightarrow \exp(-\omega t) A^*S^*(t)u_0$ coincide with that of $t \rightarrow \exp(-\omega t) |A^*S^*(t)u_0|_{-1}$ (see [12, proof of Lemma 3.1]), we infer that the function $t \rightarrow \exp(-\omega t) A^*S^*(t)u_0$ has at most countably many discontinuities. Hence, for each $u_0 \in L^2$, the function $t \rightarrow S^*(t)u_0$ is H^{-1} differentiable on $(0, \infty) \setminus N$ and

$$(2.20) \quad \frac{d}{dt} S^*(t)u_0 + A^*S^*(t)u_0 = 0, \quad \forall t \in (0, \infty) \setminus N,$$

where N is a countable subset of $(0, \infty)$.

PROOF OF THEOREM 2.1 (CONTINUED). We note first that

$$(2.21) \quad S(t)u_0 = S^*(t)u_0, \quad \forall t \geq 0, u_0 \in L^1 \cap L^2.$$

Indeed, by (2.17), it follows that if $u_0 \in L^1 \cap L^2$, then

$$|v_h^{j+1}|_1 \leq |v_h^j|_1, \quad \forall j = 0, 1, \dots,$$

and, therefore,

$$(2.22) \quad |v_h^{j+1}|_1 \leq |v_h^0|_1 = |v_0|_1, \quad \forall j.$$

This follows by multiplying equation (2.17) with $\mathcal{X}_\delta(v_h^{j+1})$ and integrating over $\mathbb{R}^d$, where $\mathcal{X}_\delta$ is defined by

$$\mathcal{X}_\delta(r) = \begin{cases} 1 & \text{for } r \geq \delta, \\ \frac{r}{\delta} & \text{for } r \in (-\delta, \delta), \\ -1 & \text{for } r \leq -\delta. \end{cases}$$

Taking into account that $v_h^{j+1} \in H^1$, we have by (2.1) that

$$\begin{aligned} (A^* v_h^{j+1}, \mathcal{X}_\delta(v_h^{j+1}))_2 &= \int_{\mathbb{R}^d} \beta'(v_h^{j+1}) |\nabla v_h^{j+1}|^2 \mathcal{X}'_\delta(v_h^{j+1}) dx \\ &\quad + \int_{[x; |v_h^{j+1}(x)| \leq \delta]} (v_h^{j+1})(D \cdot \nabla v_h^{j+1}) dx, \end{aligned}$$

which yields

$$\limsup_{\delta \rightarrow 0} (A^* v_h^{j+1}, \mathcal{X}_\delta(v_h^{j+1}))_2 \geq 0, \quad \forall j = 0, 1, \dots$$

Hence,

$$\limsup_{\delta \rightarrow \infty} \int_{\mathbb{R}^d} v_h^{j+1} \mathcal{X}_\delta(v_h^{j+1}) dx \leq |v_h^j|_1, \quad \forall j = 0, 1, \dots,$$

and so (2.22) follows.

Comparing (2.17) with (1.4), we infer that $u_h \equiv v_h$, $\forall h$, and so, by (1.3) and (2.16), we get (2.21), as claimed. In particular, we have that if $u_0 \in \mathcal{P} \cap L^\infty$, then by (1.8), it also follows that $S^*(t)u_0 \in \mathcal{P} \cap L^\infty$, $\forall t > 0$.

Roughly speaking, this means that the semigroup $S(t)$ is smooth on $L^1 \cap L^2$ in H^{-1} -norm. Then, by (2.3)–(2.4), (2.21) and the corresponding properties of $S(t)$ follow by (2.12), (2.19)–(2.20). As regards (2.5)–(2.6), we note first that by [8, Theorem 4.1] (see also [10, p. 161]), we have, for all $u_0 \in \mathcal{P}$ with $u_0 \log u_0 \in L^1$,

$$(2.23) \quad E(S(t)u_0) + \int_0^t \Psi(S(\tau)u_0) d\tau \leq E(u_0) < \infty, \quad \forall t \geq 0,$$

where E is the energy functional (1.13) and

$$(2.24) \quad \Psi(u) \equiv \int_{\mathbb{R}^d} \left| \frac{\beta'(u) \nabla u}{\sqrt{b^*(u)}} - D \sqrt{b^*(u)} \right|^2 dx.$$

Hence, $\Psi(S^*(t)u_0) < \infty$, a.e. $t > 0$, which by (2.21) and hypotheses (i)–(iii) implies (2.5) (see [8, Lemma 5.1]), as claimed. Moreover, by (2.23), also (2.6) holds.

Assume now that $u_0 \in \mathcal{P}^*$; hence, $\frac{\psi}{u_0} \in L^1$ for some $\psi \in \mathcal{X}$, where $\mathcal{X}$ is defined by (1.15). We note that since $S(t)(\mathcal{P}) \subset \mathcal{P}$, $\forall t \geq 0$, we have also that $u(t) \geq 0$, $\forall t \geq 0$, and $u(t) \in L^\infty$, $\forall t \geq 0$. So, it remains to prove that $\frac{\psi}{u(t)} \in L^1$, $\forall t \geq 0$. To this end, we consider the cut-off function

$$\varphi_n(x) = \eta\left(\frac{|x|^2}{n}\right) \psi(x), \quad \forall x \in \mathbb{R}^d, \quad n \in \mathbb{N},$$

where $\eta \in C^2([0, \infty))$ is such that $0 \leq \eta \leq 1$ and

$$(2.25) \quad \eta(r) = 1, \quad \forall r \in [0, 1]; \quad \eta(r) = 0, \quad \forall r \geq 2.$$

Since $u : [0, \infty) \rightarrow H^{-1}$ is locally Lipschitz, $[0, \infty) \ni t \rightarrow {}_{H^{-1}}(u(t), \varphi)_{H^1}$ is locally Lipschitz for all $\varphi \in H^1$, and so almost everywhere differentiable. We also note the chain differentiation rule

$$\frac{d}{dt} \int_{\mathbb{R}^d} g(u(t, x)) \varphi_n(x) dx = {}_{H^{-1}} \left(\frac{du}{dt}(t), \gamma(u(t)) \varphi_n \right)_{H^1}, \quad \text{a.e. } t \in (0, T),$$

for all $T > 0$ and all $u \in L^2(0, T; H^1)$, with $\frac{du}{dt} \in L^2(0, T; H^{-1})$, where $\gamma \in C^1(\mathbb{R})$, $g(r) \equiv \int_0^r \gamma(s) ds$.

In the special case, where $\frac{du}{dt} \in L^2(0, T; L^2)$, this formula follows by [4, Lemma 4.4, p. 158]. If $\frac{du}{dt} \in L^2(0, T; H^{-1})$, this follows by approximating u by $u_\varepsilon = (I - \varepsilon \Delta)^{-1} u$ and letting $\varepsilon \rightarrow 0$. We also note that by (2.15) we have that

$$u = S^*(t)u_0 \in L^2(0, T; H^1).$$

Let $\varepsilon > 0$ be arbitrary, but fixed. Then, since $(u(\cdot) + \varepsilon)^{-1} \in L^2(0, T; H^1)$, we have

$$-\frac{d}{dt} \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx = {}_{H^{-1}} \left(\frac{du}{dt}(t), \frac{\varphi_n}{(u(t) + \varepsilon)^2} \right)_{H^1}, \quad \text{a.e. } t > 0,$$

and so, by (2.14), we get

$$\begin{aligned} (2.26) \quad & \frac{d}{dt} \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx + 2 \int_{\mathbb{R}^d} \frac{\beta'(u(t, x)) \varphi_n(x) |\nabla u(t, x)|^2}{(u(t, x) + \varepsilon)^3} dx \\ &= \int_{\mathbb{R}^d} \frac{\beta'(u(t, x)) (\nabla \varphi_n(x) \cdot \nabla u(t, x))}{(u(t, x) + \varepsilon)^2} dx \\ &\quad - \int_{\mathbb{R}^d} \frac{(D(x) \cdot \nabla \varphi_n(x)) b(u(t, x)) u(t, x)}{(u(t, x) + \varepsilon)^2} dx \\ &\quad + 2 \int_{\mathbb{R}^d} \frac{b(u(t, x)) u(t, x) (D(x) \cdot \nabla u(t, x)) \varphi_n(x)}{(u(t, x) + \varepsilon)^3} dx, \quad \text{a.e. } t > 0. \end{aligned}$$

By (2.25), we have

$$|\nabla \varphi_n(x)| \leq \frac{4\psi(x)}{\sqrt{n}} |\eta'|_\infty + \varphi_n(x) g(x), \quad x \in \mathbb{R}^d,$$

where $g(x) = \frac{|\nabla \psi(x)|}{\psi(x)}$.

On the other hand, we have by hypotheses (i)–(iii) that

$$(2.27) \quad 2 \int_{\mathbb{R}^d} \frac{\beta'(u(t, x)) \varphi_n(x) |\nabla u(t, x)|^2}{(u(t, x) + \varepsilon)^3} dx \geq 2\gamma_1 \int_{\mathbb{R}^d} \frac{\varphi_n(x) |\nabla u(t, x)|^2}{(u(t, x) + \varepsilon)^3} dx,$$

and

$$\begin{aligned}
 (2.28) \quad & \int_{\mathbb{R}^d} \frac{\beta'(u(t, x)) \nabla \varphi_n(x) \cdot \nabla u(t, x)}{(u(t, x) + \varepsilon)^2} dx \\
 & \leq \gamma_2 \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)|}{(u(t, x) + \varepsilon)^2} \left(\frac{4\psi(x)}{\sqrt{n}} |\eta'|_\infty + \varphi_n(x) g(x) \right) dx \\
 & \leq C_1 \gamma_2 \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)| \varphi_n(x)}{(u(t, x) + \varepsilon)^2} dx + \frac{C_2 \gamma_2}{\sqrt{n}} \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)| \psi(x)}{(u(t, x) + \varepsilon)^2} dx \\
 & \leq \frac{\gamma_1}{2} \int_{\mathbb{R}^d} \frac{\varphi_n(x) |\nabla u(t, x)|^2}{(u(t, x) + \varepsilon)^3} dx + \frac{C_2 \gamma_2}{\sqrt{n}} \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)| \psi(x)}{(u(t, x) + \varepsilon)^2} dx \\
 & \quad + C_3 \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx,
 \end{aligned}$$

$$\begin{aligned}
 (2.29) \quad & \int_{\mathbb{R}^d} \frac{D(x) \cdot \nabla \varphi_n(x) b(u(t, x)) u(t, x)}{(u(t, x) + \varepsilon)^2} dx \\
 & \leq C_4 \int_{\mathbb{R}^d} \frac{|\nabla \varphi_n(x)|}{u(t, x) + \varepsilon} dx \\
 & \leq C_5 \int_{\mathbb{R}^d} \left(\frac{\varphi_n(x)}{u(t, x) + \varepsilon} + \frac{\psi(x)}{\sqrt{n}(u(t, x) + \varepsilon)} \right) dx,
 \end{aligned}$$

$$\begin{aligned}
 (2.30) \quad & 2 \int_{\mathbb{R}^d} \frac{b(u(t, x)) u(t, x) (D(x) \cdot \nabla u(t, x)) \varphi_n(x)}{(u(t, x) + \varepsilon)^3} dx \\
 & \leq C_6 \gamma_3 \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)| \varphi_n(x)}{(u(t, x) + \varepsilon)^2} dx \\
 & \leq \frac{\gamma_1}{2} \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)|^2 \varphi_n(x)}{(u(t, x) + \varepsilon)^3} dx + C_7 \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx.
 \end{aligned}$$

Then, by (2.27)–(2.30) and by hypotheses (i)–(iii), it follows that

$$\begin{aligned}
 & \frac{d}{dt} \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx + \gamma_1 \int_{\mathbb{R}^d} \frac{\varphi_n(x) |\nabla u(t, x)|^2}{(u(t, x) + \varepsilon)^3} dx \\
 & \leq C_8 \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx + \frac{C_8}{\sqrt{n}} \int_{\mathbb{R}^d} \frac{\psi(x)}{u(t, x) + \varepsilon} dx \\
 & \quad + \frac{C_8}{\sqrt{n}} \int_{\mathbb{R}^d} \frac{|\nabla u(t, x)| \psi(x)}{(u(t, x) + \varepsilon)^2} dx, \quad \text{a.e. } t > 0.
 \end{aligned}$$

This yields

$$\begin{aligned}
& \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(t, x) + \varepsilon} dx + \gamma_1 \int_0^t \int_{\mathbb{R}^d} \frac{\varphi_n(x) |\nabla u(s, x)|^2}{(u(s, x) + \varepsilon)^3} dx ds \\
& \leq \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u_0(x) + \varepsilon} dx + C_9 \int_0^t ds \int_{\mathbb{R}^d} \frac{\varphi_n(x)}{u(s, x) + \varepsilon} dx \\
& \quad + \frac{C_9}{\sqrt{n}} \int_0^t ds \int_{\mathbb{R}^d} \frac{\psi(x)}{u(s, x) + \varepsilon} dx \\
& \quad + \frac{C_9}{\sqrt{n}} \int_0^t ds \int_{\mathbb{R}^d} \frac{|\nabla u(s, x)| \psi(x)}{(u(s, x) + \varepsilon)^2} dx ds, \quad \forall t \geq 0,
\end{aligned}$$

while

$$\begin{aligned}
& \int_0^T \int_{\mathbb{R}^d} \frac{|\nabla u(s, x)| \psi(x)}{(u(s, x) + \varepsilon)^2} dx ds \\
& \leq \frac{1}{\varepsilon^2} \left(\int_0^T ds \int_{\mathbb{R}^d} |\nabla u(s, x)|^2 dx \right)^{\frac{1}{2}} \left(T \int_{\mathbb{R}^d} \psi^2(x) dx \right)^{\frac{1}{2}} \leq \frac{C_{10}}{\varepsilon^2},
\end{aligned}$$

because by (2.15) we know that $\nabla u \in L^2(0, T; L^2)$.

Letting $n \rightarrow \infty$, we get

$$\int_{\mathbb{R}^d} \frac{\psi(x)}{u(t, x) + \varepsilon} dx \leq \int_{\mathbb{R}^d} \frac{\psi(x)}{u_0(x) + \varepsilon} dx + C_T \int_0^t ds \int_{\mathbb{R}^d} \frac{\psi(x)}{u(s, x) + \varepsilon} dx, \quad \forall t \in (0, T),$$

where $C_T > 0$ is independent of ε , and so, for $\varepsilon \rightarrow 0$, it follows by Gronwall's lemma (which is applicable since $\psi \in L^1$) and by Fatou's lemma that

$$\int_{\mathbb{R}^d} \frac{\psi(x)}{u(t, x)} dx \leq \exp(C_T t) \int_{\mathbb{R}^d} \frac{\psi(x)}{u_0(x)} dx < \infty, \quad \forall t \in (0, T),$$

as claimed. ■

3. A NEW TANGENT SPACE TO $\mathcal{P}$

To represent NFPE (1.1) as a gradient flow as in [16, 17], we shall interpret the space $\mathcal{P}^*$ as a Riemannian manifold endowed with an appropriate tangent bundle with scalar product which is, however, different from the one in [16, 17]. To this purpose, we define the tangent space $\mathcal{T}_u(\mathcal{P}^*)$ at $u \in \mathcal{P}^* \subset \mathcal{P}$ as follows:

$$(3.1) \quad \mathcal{T}_u(\mathcal{P}^*) = \{z = -\operatorname{div}(b^*(u) \nabla y); y \in W_{\operatorname{loc}}^{1,1}(\mathbb{R}^d), \sqrt{u} \nabla y \in L^2\} (\subset H^{-1}).$$

(Here, $\mathcal{P}^*$ is defined by (1.14).)

The differential structure of the manifold $\mathcal{P}^*$ is defined by providing for $u \in \mathcal{P}^*$ the linear space $\mathcal{T}_u(\mathcal{P}^*)$ with the scalar product (metric tensor)

$$(3.2) \quad \begin{aligned} \langle z_1, z_2 \rangle_u &= \int_{\mathbb{R}^d} b^*(u) \nabla y_1 \cdot \nabla y_2 \, dx, \\ z_i &= \operatorname{div} (b^*(u) \nabla y_i), \quad i = 1, 2, \end{aligned}$$

and with the corresponding Hilbertian norm $\|\cdot\|_u$,

$$(3.3) \quad \|z\|_u^2 = \int_{\mathbb{R}^d} b^*(u) |\nabla y|^2 \, dx, \quad z = -\operatorname{div} (b^*(u) \nabla y).$$

As a matter of fact, $\mathcal{T}_u(\mathcal{P}^*)$ is viewed here as a factor space by identifying in (3.2) two functions $y_1, y_2 \in W_{\text{loc}}^{1,1}$ if $\operatorname{div} (b^*(u) \nabla (y_1 - y_2)) \equiv 0$. Note also that, since $b^*(u) \geq b_0 u$ and $u > 0$, a.e. on $\mathbb{R}^d$, $\|z\|_u = 0$ implies that $z \equiv 0$. Moreover, we have

$$(3.4) \quad \|z_1\|_u = \|z_2\|_u \quad \text{for } z_i = \operatorname{div} (b^*(u) \nabla y_i), \quad i = 1, 2,$$

if $\operatorname{div} (b^*(u) \nabla (y_1 - y_2)) \equiv 0$ in H^{-1} . Indeed, for each $\varphi \in C_0^\infty(\mathbb{R}^d)$, we have in this case that

$$\int_{\mathbb{R}^d} b^*(u) \nabla (y_1 - y_2) \cdot \nabla (\varphi y_i) \, dx = 0, \quad i = 1, 2,$$

and this yields

$$(3.5) \quad \int_{\mathbb{R}^d} b^*(u) \nabla (y_1 - y_2) \cdot (\varphi \nabla y_i + y_i \nabla \varphi) \, dx = 0, \quad i = 1, 2.$$

If we take $\varphi(x) = \eta(\frac{|x|^2}{n})$, where $\eta \in C^2([0, \infty))$, $\eta(r) = 1$ for $0 \leq r \leq 1$, $\eta(r) = 0$ for $r \geq 2$, and let $n \rightarrow \infty$ in (3.5), we get via the Lebesgue dominated convergence theorem that

$$\int_{\mathbb{R}^d} b^*(u) \nabla (y_1 - y_2) \cdot \nabla y_i \, dx = 0, \quad i = 1, 2,$$

which, as easily seen, implies (3.4), as claimed. Hence, the norm $\|z\|_u$ is independent of representation (3.2) for z . We should also note that $\mathcal{T}_u(\mathcal{P}^*)$ so defined is a Hilbert space; in particular, it is complete in the norm $\|\cdot\|_u$. Here is the argument.

Let $u \in \mathcal{P}^*$ and let $\{y_n\} \subset W_{\text{loc}}^{1,1}$ be such that

$$\|z_n - z_m\|_u^2 = \int_{\mathbb{R}^d} b^*(u) |\nabla (y_n - y_m)|^2 \, dx \rightarrow 0 \quad \text{as } n, m \rightarrow \infty.$$

This implies that the sequence $\{\sqrt{b^*(u)} \nabla y_n\}$ is convergent in L^2 as $n \rightarrow \infty$ and by hypothesis (ii) so is $\{\sqrt{u} \nabla y_n\}$. Let

$$(3.6) \quad f = \lim_{n \rightarrow \infty} \sqrt{b^*(u)} \nabla y_n \quad \text{in } L^2.$$

As $\frac{\psi}{u} \in L^1$ for some $\psi \in \mathcal{X}$, we infer that $\{\nabla y_n\}$ is convergent in L^1_{loc} and so, by the Sobolev embedding theorem (see, e.g., [11, p. 278]), the sequence $\{y_n\}$ is convergent in $L^{\frac{d}{d-1}}_{\text{loc}}$ and, therefore, in L^1_{loc} too. Hence, as $n \rightarrow \infty$, we have

$$\begin{aligned} y_n &\rightarrow y && \text{in } L^1_{\text{loc}} \cap L^{\frac{d}{d-1}}_{\text{loc}}, \\ \nabla y_n &\rightarrow \nabla y && \text{in } (L^1_{\text{loc}})^d, \end{aligned}$$

hence, along a subsequence, a.e. on $\mathbb{R}^d$. So, by (3.6), we infer that $f = \sqrt{b^*(u)} \nabla y$, where $y \in W^{1,1}_{\text{loc}}$. Hence, as $n \rightarrow \infty$, we have

$$\|z_n - z\|_u \rightarrow 0 \quad \text{for } z = -\operatorname{div}(b^*(u)\nabla y), \quad y \in W^{1,1}_{\text{loc}},$$

as claimed.

As a consequence, we have that

$$(3.7) \quad \{z = -\operatorname{div}(b^*(u)\nabla y); y \in C_0^\infty(\mathbb{R}^d)\} \text{ is dense in } \mathcal{T}_u(\mathcal{P}^*) \text{ for all } u \in \mathcal{P}^*.$$

To conclude, we have shown that, for each $u \in \mathcal{P}^*$, $\mathcal{T}_u(\mathcal{P}^*)$ is a Hilbert space with the scalar product (3.2) and, as mentioned earlier, this is just the *tangent space* to $\mathcal{P}^*$ at u .

4. THE FOKKER-PLANCK GRADIENT FLOW ON $\mathcal{P}^*$

We are going to define here the $\mathcal{T}_u(\mathcal{P}^*)$ -gradient $\nabla E_u : \mathcal{T}_u(\mathcal{P}^*) \rightarrow \mathcal{F}_u(\mathcal{P}^*) \subset H^{-1}$ of the energy function $E : L^2 \rightarrow]-\infty, +\infty]$ defined by (1.13), that is,

$$E(u) = \begin{cases} \int_{\mathbb{R}^d} (\eta(u) + \Phi u) dx & \text{if } u \in \mathcal{P} \cap L^\infty(\mathbb{R}^d) \cap L^1(\mathbb{R}^d; \Phi dx) \\ +\infty & \text{otherwise.} \end{cases}$$

We note that E is convex, nonidentically $+\infty$, and we have the following result.

LEMMA 4.1. *E is lower-semicontinuous on L^2 .*

PROOF. We first note that if $u \in \mathcal{P} \cap L^\infty \cap L^1(\mathbb{R}^d; \Phi dx)$, then by the proof of (4.6) in [8] for all $\alpha \in [m/(m+1), 1)$, we have by hypothesis (iv)

$$\int_{\mathbb{R}^d} \eta(u) dx \geq -C_\alpha \left(\int_{\mathbb{R}^d} \Phi u dx + 1 \right)^\alpha;$$

hence, since $r^\alpha \leq \frac{1}{2C_\alpha} r + C'_\alpha$, $r \geq 0$,

$$(4.1) \quad E(u) \geq \frac{1}{2} \int_{\mathbb{R}^d} \Phi u dx - C''_\alpha$$

for some $C_\alpha, C'_\alpha, C''_\alpha \in (0, \infty)$ independent of u .

Let now $u, u_n \in L^2$, $n \in \mathbb{N}$, such that $\lim_{n \rightarrow \infty} u_n = u$ in L^2 . We may assume that

$$\liminf_{n \rightarrow \infty} E(u_n) = \lim_{n \rightarrow \infty} E(u_n) < \infty$$

and that $E(u_n) < \infty$ for all $n \in \mathbb{N}$. Then, by (4.1),

$$(4.2) \quad \sup_{n \in \mathbb{N}} \int_{\mathbb{R}^d} \Phi u_n dx < \infty.$$

Now, suppose that

$$(4.3) \quad E(u) > \lim_{n \rightarrow \infty} E(u_n).$$

Then

$$\begin{aligned} E(u) &> \liminf_{n \rightarrow \infty} \int_{\mathbb{R}^d} \eta(u_n) dx + \liminf_{n \rightarrow \infty} \int_{\mathbb{R}^d} \Phi u_n dx \\ &\geq \liminf_{n \rightarrow \infty} \int_{\mathbb{R}^d} \eta(u_n) dx + \int_{\mathbb{R}^d} \Phi u dx, \end{aligned}$$

where we applied Fatou's lemma to the second summand in the last inequality. If we can also apply it to the first, then we get a contradiction to (4.3) and the lemma is proved. To justify the application of Fatou's lemma to the first summand, it is enough to prove that there exist $f_n \in L^1$, $n \in \mathbb{N}$, $f_n \geq 0$, such that (along a subsequence)

$$(4.4) \quad f_n \rightarrow f \quad \text{in } L^1,$$

and

$$(4.5) \quad \eta(u_n) \geq -f_n, \quad n \in \mathbb{N}.$$

To find such f_n , $n \in \mathbb{N}$, we use (4.2). Recall from [8, (4.4)] that, for some $c \in (0, \infty)$,

$$\eta(r) \geq -cr \log^-(r) - cr, \quad r \geq 0.$$

Hence,

$$\eta(u_n) \geq -cu_n \log^-(u_n) - cu_n, \quad n \in \mathbb{N}.$$

Since $u_n \rightarrow u$ in L^2 and thus in L^1_{loc} , it follows by (4.2) and our assumptions on Φ that (again along a subsequence) $u_n \rightarrow u$ in L^1 . Furthermore, for all $\alpha \in (0, 1)$,

$$\begin{aligned} -f \log^-(r) &= 1_{[0,1]}(r) r \log r \\ &= 1_{[0,1]}(r) r \frac{1}{1-\alpha} r^\alpha \underbrace{r^{1-\alpha} \log r^{1-\alpha}}_{\geq -e^{-1}} \geq -\frac{1}{(1-\alpha)e} r^\alpha, \quad r \geq 0. \end{aligned}$$

Hence, we find that

$$\eta(u_n) \geq -\frac{c}{(1-\alpha)e} u_n^\alpha - cu_n, \quad n \in \mathbb{N}.$$

But, since $u_n \rightarrow u$ in L^2 and thus $u_n^\alpha \rightarrow u^\alpha$ in L^1_{loc} , by hypothesis (iv), it remains to show that, for some $\varepsilon, \alpha \in (0, 1)$,

$$(4.6) \quad \sup_{n \in \mathbb{N}} \int_{\mathbb{R}^d} u_n^\alpha \Phi^\varepsilon dx < \infty,$$

to conclude that (along a subsequence) $u_n^\alpha \rightarrow u^\alpha$ in L^1 , and then (again selecting a subsequence of $\{u_n\}$ if necessary) (4.4) and (4.5) hold with

$$f_n := \frac{c}{(1-\alpha)e} u_n^\alpha + cu_n, \quad n \in \mathbb{N}.$$

So, let us prove (4.6).

Applying Hölder's inequality with $p := \frac{1}{\alpha}$, we find that

$$\int_{\mathbb{R}^d} u_n^\alpha \Phi^\varepsilon dx \leq \left(\int_{\mathbb{R}^d} u_n \Phi dx \right)^\alpha \left(\int_{\mathbb{R}^d} \Phi^{-(\frac{1}{\alpha}-\varepsilon)/(1-\alpha)} dx \right)^{1-\alpha}.$$

Hence, choosing ε small enough and α close enough to 1, so that $(\frac{1}{\alpha}-\varepsilon)/(1-\alpha) \geq m$, hypothesis (iv) implies (4.6). ■

By Lemma 4.1, we have for E that its directional derivative

$$E'(u, z) = \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} (E(u + \lambda z) - E(u))$$

exists for all $u \in \mathcal{P}^*$ and $z \in L^2$ (it is unambiguously either a real number or $+\infty$) (see, e.g., [6, p. 86]).

In the following, we shall take $u \in \mathcal{P}^* \subset D(E) = \{u \in L^2; E(u) < \infty\}$ and $z \in \mathcal{T}_u(\mathcal{P}^*)$ and obtain that

$$(4.7) \quad \begin{aligned} E'(u, z) &= \lim_{\lambda \downarrow 0} \frac{1}{\lambda} (E(u + \lambda z) - E(u)) \\ &= \int_{\mathbb{R}^d} z(x) \left(\int_1^{u(x)} \frac{\beta'(\tau)}{b^*(\tau)} d\tau + \Phi(x) \right) dx. \end{aligned}$$

Moreover, the subdifferential $\partial E_u : L^2 \rightarrow L^2$ of E at u is expressed as (see [6, Proposition 2.39])

$$(4.8) \quad \partial E_u = \{y \in L^2; (z, y)_2 \leq E'(u, z); \forall z \in L^2\}.$$

We recall that if E is Gâteaux differentiable at u , then ∂E_u reduces to the L^2 -gradient $\nabla E_u \in L^2$ of E at u defined by

$$(4.9) \quad E'(u, z) = (\nabla E_u, z)_2, \quad \forall z \in L^2.$$

Any element $y \in \partial E_u$ is called a *subgradient* of E at u . In the following, we shall denote, for simplicity, again by ∇E_u any subgradient of E at u and we shall keep the notation $\text{diff } E_u \cdot z$ for $E'(u, z)$.

If $z \in \mathcal{T}_u(\mathcal{P}^*)$ is of the form $z = z_2 = -\text{div}(b^*(u)\nabla y_2)$, where $y_2 \in C_0^\infty(\mathbb{R}^d)$, then

$$z = -b^*(u)\Delta y_2 - \nabla y_2 \cdot (b'(u)u + b(u))\nabla u$$

and so, by (i) and (1.14), it follows that $z \in L^2$. Then, by (4.7), we have

$$(4.10) \quad \begin{aligned} E'(u, z) &= \text{diff } E_u \cdot z = \lim_{\lambda \downarrow 0} \frac{1}{\lambda} (E(u + \lambda z_2) - E(u)) \\ &= \int_{\mathbb{R}^d} \left(\frac{\nabla \beta(u(x))}{b^*(u(x))} - D(x) \right) b^*(u(x)) \cdot \nabla y_2(x) dx \\ &= \int_{\mathbb{R}^d} b^*(u(x)) \nabla y_2(x) \cdot \nabla \left(\int_0^{u(x)} \frac{\beta'(s)}{b^*(s)} ds + \Phi(x) \right) dx. \end{aligned}$$

We claim that

$$(4.11) \quad x \mapsto \int_0^{u(x)} \frac{\beta'(s)}{b^*(s)} ds + \Phi(x) \quad \text{in } W_{\text{loc}}^{1,1}.$$

To prove this, we first note that by hypotheses (i) and (ii),

$$\frac{\gamma_1}{|b|_\infty} \frac{1}{s} \leq \frac{\beta'(s)}{b^*(s)} \leq \frac{\gamma_2}{b_0} \frac{1}{s}, \quad s > 0.$$

Hence,

$$(4.12) \quad \frac{\gamma_1}{|b|_\infty} \log u \leq \int_0^u \frac{\beta'(s)}{b^*(s)} ds \leq \frac{\gamma_2}{b_0} \log u.$$

Now, let $\psi \in \mathcal{X}$ such that $\frac{\psi}{u} \in L^1$. Then, for every compact $K \subset \mathbb{R}^d$ and $K_n := \{\frac{1}{n} \leq u \leq 1\}$, $n \in \mathbb{N}$,

$$\begin{aligned} \int_{K_n} (\log u)^- dx &\leq \left(\int_{K_n} (\log u)^2 u dx \right)^{\frac{1}{2}} (\inf_K \psi)^{-\frac{1}{2}} \left(\int_K \frac{\psi}{u} dx \right)^{\frac{1}{2}} \\ &\leq \sup_K ((\log u)^- u) \left(\int_{K_n} (\log u)^- dx \right)^{\frac{1}{2}} (\inf_K \psi)^{-\frac{1}{2}} \left(\int_K \frac{\psi}{u} dx \right)^{\frac{1}{2}}. \end{aligned}$$

Dividing by $(\int_{K_n} (\log u)^- dx)^{\frac{1}{2}}$ and letting $n \rightarrow \infty$ yields $\log u \in L^1_{\text{loc}}$ since trivially $(\log u)^+ \in L^1_{\text{loc}}$ since $u \in L^\infty$. Furthermore, for $\varepsilon > 0$,

$$\int_K |\nabla \log(u + \varepsilon)| dx \int_K \frac{|\nabla u|}{u + \varepsilon} dx \leq \left(\int_K \frac{|\nabla u|^2}{u} dx \right)^{\frac{1}{2}} \left(\inf_K \psi \right)^{-\frac{1}{2}} \left(\int_K \frac{\psi}{u} dx \right)^{\frac{1}{2}}.$$

Letting $\varepsilon \rightarrow 0$ yields $|\nabla \log u| \in L^1_{\text{loc}}$, and (4.11) is proved by hypothesis (iv). Hence, by (4.10),

$$E'(u, z_2) = \int_{\mathbb{R}^d} b^*(u(x)) \nabla y_2(x) \cdot \nabla y_1(x) dx = -\langle z_1, z_2 \rangle_u,$$

where $z_1 = -\text{div}(b^*(u) \nabla y_1)$, $y_1 = \int_0^u \frac{\beta'(s)}{b^*(s)} ds + \Phi$. Therefore, the functional

$$z_2 \mapsto E'(u, z_2) = \text{diff } E_u z_2$$

extends by continuity to all $z = z_2 \in \mathcal{T}_u(\mathcal{P}^*)$ and by (3.2) it follows that for $u^* \in \mathcal{P}^*$ there is $\nabla E_u \in \mathcal{T}_u(\mathcal{P}^*) \subset H^{-1}$ such that

$$\text{diff}(E_u z_2) = (\nabla E_u, z_2)_u$$

and

$$\begin{aligned} (4.13) \quad \nabla E_u &= -\text{div} \left(b^*(u) \nabla \left(\int_0^u \frac{\beta'(s)}{b^*(s)} ds + \Phi \right) \right) \\ &= -\Delta \beta(u) + \text{div} (D b^*(u)) \in H^{-1}. \end{aligned}$$

This is by definition the $\mathcal{T}_u(\mathcal{P}^*)$ -gradient of E at u . Though, for simplicity, we have denoted it again by ∇E_u , it should be mentioned that it does not coincide with the L^2 -gradient defined by (4.9).

On the other hand, by Theorem 2.1, we know that, for $u_0 \in \mathcal{P}^*$ with $u_0 \log u_0 \in L^1$, we have for the flow $u(t) \equiv S(t)u_0$,

$$S(t)u_0 \in H^1 \cap \mathcal{P}, \quad \forall t > 0, \quad \frac{\nabla(S(t)u_0)}{\sqrt{S(t)u_0}} \in L^2, \quad \text{a.e. } t > 0,$$

$$(4.14) \quad \frac{d^+}{dt} S(t)u_0 = \Delta \beta(S(t)u_0) - \text{div} (D b^*(S(t)u_0)), \quad \forall t > 0,$$

$$(4.15) \quad \frac{d}{dt} S(t)u_0 = \Delta \beta(S(t)u_0) - \text{div} (D b^*(S(t)u_0)), \quad \forall t \in (0, \infty) \setminus N,$$

where N is at most countable set of $(0, \infty)$. Moreover, if $u_0 \in \mathcal{P}^*$, then, as seen in Theorem 2.1, it follows that $S(t)u_0 \in \mathcal{P}^*$, $\forall t > 0$, and $\nabla E_{u(t)}$ is well defined, a.e. $t > 0$. Taking into account (4.13), we may rewrite (4.14)–(4.15) as the gradient flow on $\mathcal{P}^*$ endowed with the metric tensor (3.2). Namely, we have the following theorem.

THEOREM 4.2. *Under hypotheses (i)–(iv), for each $u_0 \in \mathcal{P}^*$, the function $u(t) = S(t)u_0 \in \mathcal{P}^*$, $\forall t > 0$, and it is the solution to the gradient flow*

$$(4.16) \quad \frac{d}{dt} u(t) = -\nabla E_{u(t)}, \quad a.e. \ t > 0,$$

$$(4.17) \quad \frac{d^+}{dt} u(t) = -\nabla E_{u(t)}, \quad \forall t > 0,$$

$$(4.18) \quad \frac{d}{dt} u(t) = -\nabla E_{u(t)}, \quad \forall t \in (0, \infty) \setminus N,$$

where N is at most countable set of $(0, \infty)$.

By (3.2), we may rewrite (4.17) as

$$(4.19) \quad \frac{d^+}{dt} E(S(t)u_0) = -\left\| \frac{d^+}{dt} S(t)u_0 \right\|_{u(t)}^2, \quad \forall t > 0.$$

Equivalently,

$$(4.20) \quad \frac{d^+}{dt} E(S(t)u_0) + A(S(t)u_0) = 0, \quad \forall t > 0,$$

where A^* is the generator (2.1) of the Fokker–Planck semigroup $S^*(t)$ (equivalently, $S(t)$) in H^{-1} . Similarly, by (3.3) and (2.23)–(2.24), we can write

$$(4.21) \quad \frac{d}{dt} E(S(t)u_0) = -\left\| \frac{d}{dt} S(t)u_0 \right\|_{u(t)}^2 = \Psi(S(t)u_0), \quad \forall t \in (0, \infty) \setminus N.$$

As a matter of fact, the energy dissipation formula (4.21) was used in [8] (see also [5, Chapter 4]) to prove that $S(t)u_0 \rightarrow u_\infty$ strongly in L^1 as $t \rightarrow \infty$, where u_∞ is the unique solution to equilibrium equation $-\Delta \beta(u_\infty) + \operatorname{div}(Db(u_\infty)u_\infty) = 0$.

REMARK 4.3. Taking into account (4.7), we see also that the operator A^* defined by (2.1) can be expressed as

$$(4.22) \quad A^*u = B_u \operatorname{diff} E_u, \quad \forall u \in D(A^*) = H^1,$$

where $B_u : H^1 \rightarrow H^{-1}$ is the linear symmetric operator defined by

$$(4.23) \quad \begin{aligned} B_u(y) &= -\operatorname{div}(b^*(u)\nabla y), \quad \forall y \in D(B_u), \\ D(B_u) &= \{y \in l^2, \sqrt{u}\nabla y \in L^2\}. \end{aligned}$$

This means that ∇E_u can be equivalently written as

$$(4.24) \quad \nabla E_u = B_u(\operatorname{diff} E_u).$$

In the special case $b(r) \equiv 1$,

$$E_u \equiv \int_1^u \frac{\beta'(\tau)}{\tau} d\tau + \Phi$$

and so $u(t) = S(t)u_0$ is the Wasserstein gradient flow of the functional E defined by the time-discretized scheme

$$u_h(t) = u_h^j, \quad t \in [jh, (j+1)h), \quad j = 0, 1, \dots,$$

$$u_h^j = \min_u \left\{ \frac{1}{2h} d_2(u, u_h^{j-1}) + E(u) \right\},$$

where d_2 is the Wasserstein distance of order two (see [3, 14, 16]). However, in the general case considered here, this is not the case.

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Viorel Barbu

Alexandru Ioan Cuza University

700506 Iași

Octav Mayer Institute of Mathematics, Romanian Academy

700505 Iași, Romania

vbarbu41@gmail.com

Michael Röckner

Faculty of Mathematics, Bielefeld University

33615 Bielefeld, Germany

Academy of Mathematics and Systems Science, Chinese Academy of Sciences

100190 Beijing, P. R. China

roeckner@math.uni-bielefeld.de